

# Introduction to Optimization

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# Why Optimization?

## Core Idea

In many real-world problems, we want to:

**find the best possible decision**

- What is the **shortest route** between cities?
- How to train a model with **minimum error**?
- How to allocate resources **efficiently**?
- How to design systems with **best performance**?

## Key Question

How can we systematically find the best solution?

# Motivating Example: Finding the Best Route

## Problem

You want to visit several cities:

Lyon, Madrid, Mexico, Buenos Aires, La Paz

- Many possible routes:
  - Lyon  $\rightarrow$  Buenos Aires  $\rightarrow$  La Paz  $\rightarrow$  Madrid  $\rightarrow$  Mexico
  - Madrid  $\rightarrow$  Mexico  $\rightarrow$  Lyon  $\rightarrow$  Buenos Aires  $\rightarrow$  La Paz
  - Lyon  $\rightarrow$  Buenos Aires  $\rightarrow$  Madrid  $\rightarrow$  Mexico  $\rightarrow$  La Paz
- Each route has a different total distance
- Goal: **find the shortest one**

## Insight

- Each route = a **candidate solution**
- Total distance = **objective function**
- We want to **minimize** it

# Optimization Problem

## Definition

Let  $f : A \rightarrow \mathbb{R}$ . A constrained optimization problem:

$$\begin{aligned} \min_{a \in A} \quad & f(a) \\ \text{s.t.} \quad & g(a) \leq 0, \quad h(a) = 0 \end{aligned}$$

- $A$ : search space
- $a$ : candidate (feasible) solution
- $f(a)$ : objective (cost / loss / utility)
- $g(a) \leq 0$  and  $h(a) = 0$ : constrains

# Minimizers and Notation

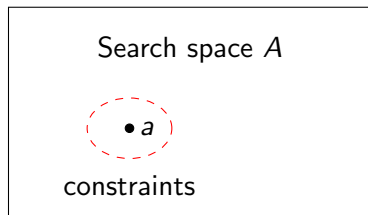
$$\text{ArgMin}_{a \in A} f(a)$$

- Set of optimal solutions
- If unique:  $a^* = \text{ArgMin } f(a)$
- Minimizer:  $f(a^*) \leq f(a)$

## Remark

Maximization : minimize  $(-f)$

# Search Space and Constraints



- Only feasible solutions are allowed
- Constraints define the search region

# Applications

- **Machine Learning:** minimize prediction error
- **Statistics:** maximize likelihood
- **Logistics:** minimize delivery distance
- **Engineering:** optimize energy consumption

## Example

Train a model by minimizing:

$$\text{error}(w) = \|Xw - y\|^2$$

# Discrete vs Continuous

## Continuous

$$A \subseteq \mathbb{R}^n$$

- Regression coefficients
- Finding a barycenter

## Discrete

- Traveling Salesman Problem (TSP)
- Knapsack problem

# Discrete Example: TSP

- Cities: Lyon, Madrid, Mexico, Buenos Aires, La Paz
- Goal: minimize total distance

(Lyon, Madrid, Mexico, . . . )

## Challenge

Number of solutions grows factorially:

$$(n - 1)!/2$$

# Local vs Global Minima

## Local Minimum

Best solution  $a^*$  in a neighborhood

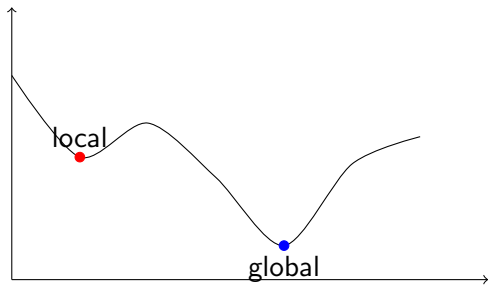
$$\exists \delta > 0 \text{ s.t. } \forall a \in A, \|a - a^*\| \leq \delta \Rightarrow f(a') \leq f(a)$$

## Global Minimum

Best solution  $a^*$  overall

$$\forall a \in A, f(a^*) \leq f(a)$$

# Illustration



# Convexity

## Definition

$$f(\lambda x + (1 - \lambda)y) \leq \lambda f(x) + (1 - \lambda)f(y)$$

- No “valleys inside valleys”
- Shape like a bowl

# Key Theorem

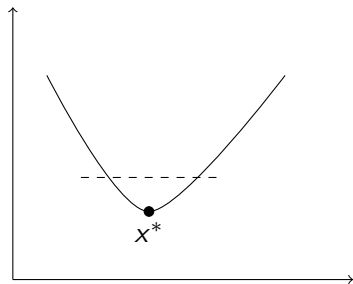
## Theorem

If  $f$  is convex:

local minimum = global minimum

- Very important in optimization
- Guarantees correctness of algorithms

# Convexity Intuition



- Tangent line lies below the function
- No better solution exists elsewhere

# Multiobjective Optimization

$$\min(f_1(a), f_2(a), \dots, f_k(a))$$

- Several objectives
- Often conflicting

# Pareto Optimality

## Dominance

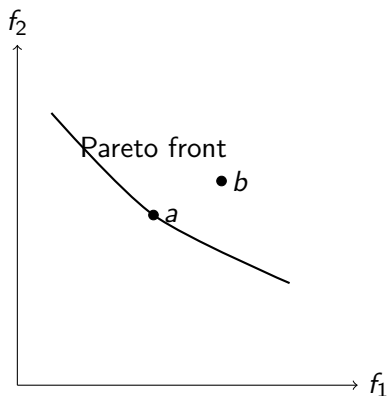
$a$  dominates  $b$  if:

$$f_i(a) \leq f_i(b) \quad \forall i$$

## Pareto Optimal

No other solution is better in all objectives

# Pareto Front



- $a$  is optimal
- $b$  is dominated

# Examples

- Car design:
  - minimize fuel consumption
  - maximize speed
- Smartphone:
  - maximize battery life
  - minimize weight
- Machine Learning:
  - minimize error
  - minimize computation cost