

Linear Systems: From Equations to Matrices

What Is a Linear System?

Definition

A **linear system** is a collection of equations where each equation expresses a linear relationship between unknown variables.

What Is a Linear System?

Definition

A **linear system** is a collection of equations where each equation expresses a linear relationship between unknown variables.

- Linear systems arise from:
 - experimental measurements,
 - physical constraints,
 - biological interactions,
 - statistical models.
- They are central to:
 - regression,
 - numerical simulation,
 - PCA and matrix factorization.

A Simple Motivating Example (Biology)

Biological setting

A metabolite is regulated by two genes:

- gene a with regulatory strength x ,
- gene b with regulatory strength y .

A Simple Motivating Example (Biology)

Biological setting

A metabolite is regulated by two genes:

- gene a with regulatory strength x ,
- gene b with regulatory strength y .

Linear model

For gene expression levels (E_a, E_b) :

$$M = xE_a + yE_b$$

A Simple Motivating Example (Biology)

Biological setting

A metabolite is regulated by two genes:

- gene a with regulatory strength x ,
- gene b with regulatory strength y .

Linear model

For gene expression levels (E_a, E_b) :

$$M = xE_a + yE_b$$

Two experiments

$$\begin{cases} 2x - y = 3 \\ x + 4y = 10 \end{cases}$$

What Is the Goal?

- Each experiment provides a **linear constraint**
- The unknowns (x, y) must satisfy *all* constraints simultaneously

What Is the Goal?

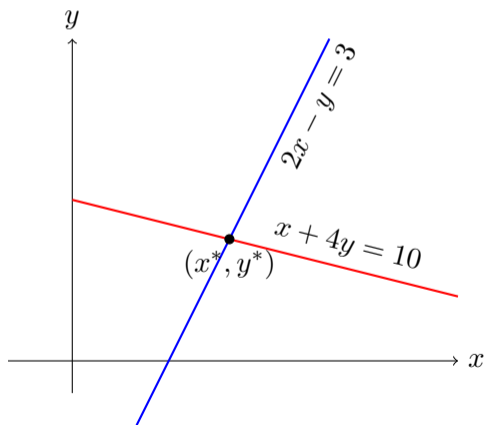
- Each experiment provides a **linear constraint**
- The unknowns (x, y) must satisfy *all* constraints simultaneously

Goal

Find the pair (x, y) that explains all experimental observations.

Geometric Interpretation

- Each equation defines a straight line in the plane
- The solution is the intersection of the lines



From Equations to Matrices

- Coefficients \rightarrow matrix
- Unknowns \rightarrow vector
- Observations \rightarrow vector

From Equations to Matrices

- Coefficients \rightarrow matrix
- Unknowns \rightarrow vector
- Observations \rightarrow vector

$$A = \begin{pmatrix} 2 & -1 \\ 1 & 4 \end{pmatrix}, \quad x = \begin{pmatrix} x \\ y \end{pmatrix}, \quad b = \begin{pmatrix} 3 \\ 10 \end{pmatrix}$$

From Equations to Matrices

- Coefficients \rightarrow matrix
- Unknowns \rightarrow vector
- Observations \rightarrow vector

$$A = \begin{pmatrix} 2 & -1 \\ 1 & 4 \end{pmatrix}, \quad x = \begin{pmatrix} x \\ y \end{pmatrix}, \quad b = \begin{pmatrix} 3 \\ 10 \end{pmatrix}$$

Compact form

$$Ax = b$$

Why Matrix Decompositions?

- Direct inversion is often:
 - numerically unstable,
 - computationally expensive.
- Modern solvers use **matrix factorizations**

Why Matrix Decompositions?

- Direct inversion is often:
 - numerically unstable,
 - computationally expensive.
- Modern solvers use **matrix factorizations**

Two key decompositions

- LU decomposition
- QR decomposition

LU Decomposition

Factorization

$$A = LU$$

- L : lower triangular (unit diagonal)
- U : upper triangular

LU Decomposition

Factorization

$$A = LU$$

- L : lower triangular (unit diagonal)
- U : upper triangular

Solving $Ax = b$

$$LUx = b$$

- 1 Forward substitution: $Ly = b$
- 2 Backward substitution: $Ux = y$

QR Decomposition

Factorization

$$A = QR$$

- Q : orthogonal matrix ($Q^T Q = I$)
- R : upper triangular

QR Decomposition

Factorization

$$A = QR$$

- Q : orthogonal matrix ($Q^T Q = I$)
- R : upper triangular

Solving

$$QRx = b \Rightarrow Rx = Q^T b$$

QR Decomposition

Factorization

$$A = QR$$

- Q : orthogonal matrix ($Q^T Q = I$)
- R : upper triangular

Solving

$$QRx = b \Rightarrow Rx = Q^T b$$

Why QR?

Orthogonal matrices preserve lengths:

$$\|Qx\| = \|x\|$$

Why QR Is Important

- More numerically stable than LU
- Handles:
 - ill-conditioned systems,
 - overdetermined systems ($m > n$),
 - least-squares regression.
- Central in:
 - regression,
 - eigenvalue algorithms.

Summary

Key ideas

- Linear systems model multiple constraints simultaneously
- Matrix form: $Ax = b$
- Geometry: intersection of hyperplanes

Summary

Key ideas

- Linear systems model multiple constraints simultaneously
- Matrix form: $Ax = b$
- Geometry: intersection of hyperplanes

Numerical solutions

- LU: efficient for square systems
- QR: stable and essential for least squares